



# Cross the Gap: Exposing CLIP Intra-modal misalignment Via Modality Inversion

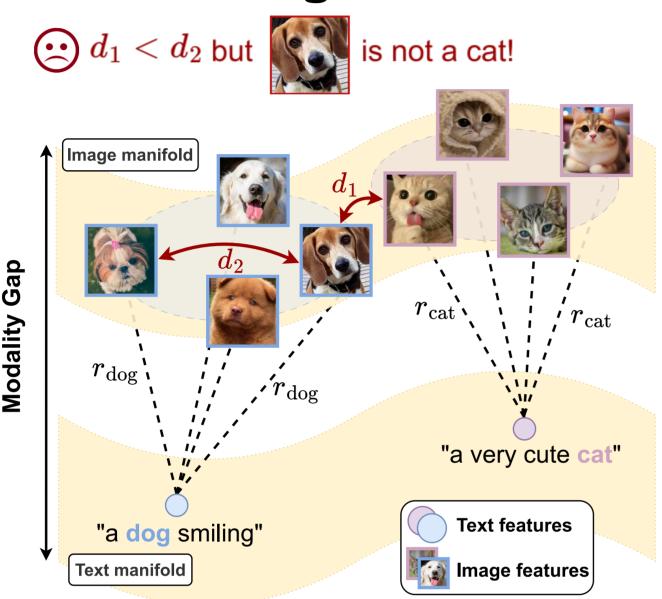


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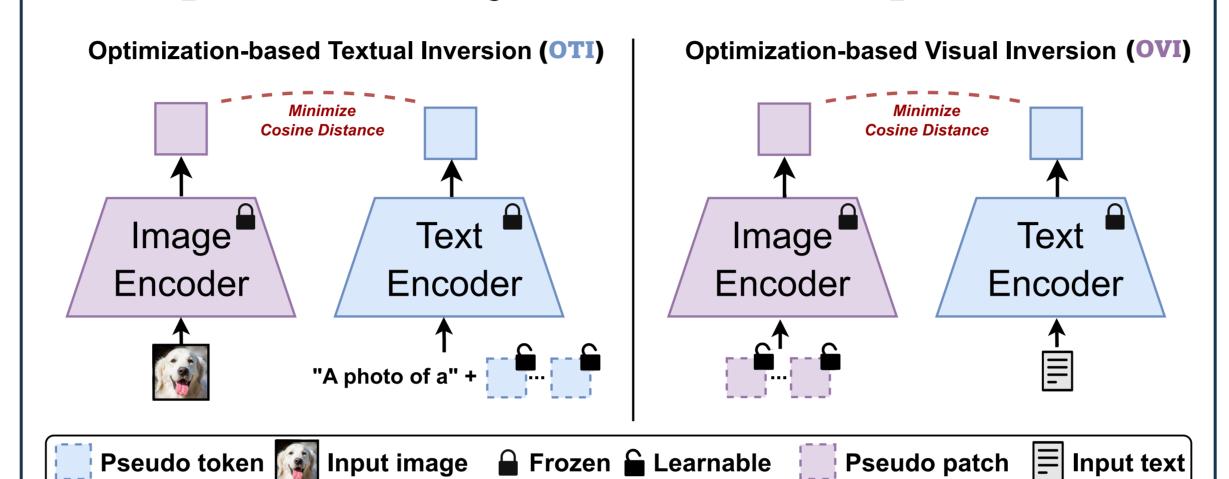
Better STOP using CLIP for image-to-image or text-to-text similarity comparisons. Intra-modal similarities are suboptimal. Mind the CLIP intra-modal misalignment!

# **−1. Defining CLIP Intra-Modal Misalignment**-

- □ VLMs (like **CLIP**) are used off-the-shelf for a variety of applications
- ☐ However, CLIP pretraining aligns *only* image-text pairs, and does not ensure that two similar images (or texts) are close to each other
- ☐ An image of a dog might end up closer to an image of a cat than to another dog.
- ☐ We call this overseen issue intra-modal misalignment



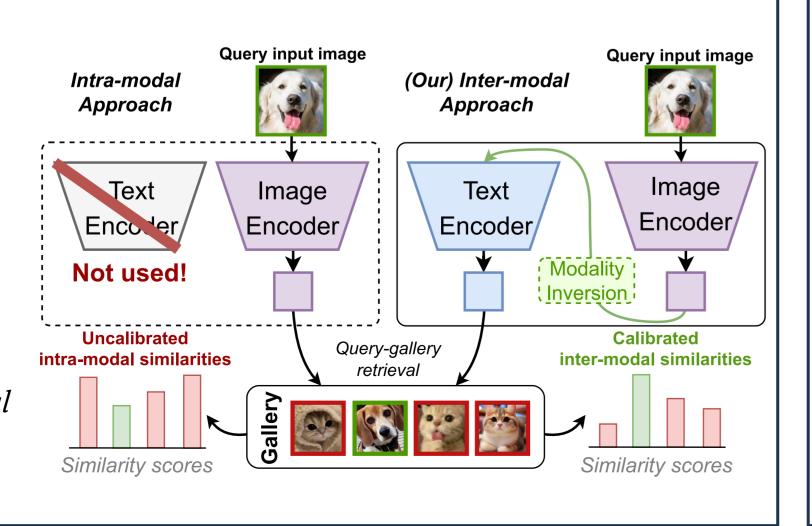
# -3. Proposed modality inversion techniques



Both inversion techniques are single-feature level, freeze the backbones, and optimize a few parameters by minimizing the *cosine distance* with the input feature

# 2. How to go from intra-modal to inter modal?

- ☐ CLIP features are widely used for **intra-modal comparisons** (e.g., image-to-image retrieval or text-to-text retrieval)
- ☐ We argue that common intra-modal methods result in uncalibrated similarities
- We introduce the usage of modality inversion techniques to approach any intra-modal task inter-modally
- ☐ This shouldn't help unless *intra-modal misalignment* is real!
- ☐ We show that *inter-modal similarities* outperform intra-modal baselines



# -4. Approach intra-modal task intermodally-

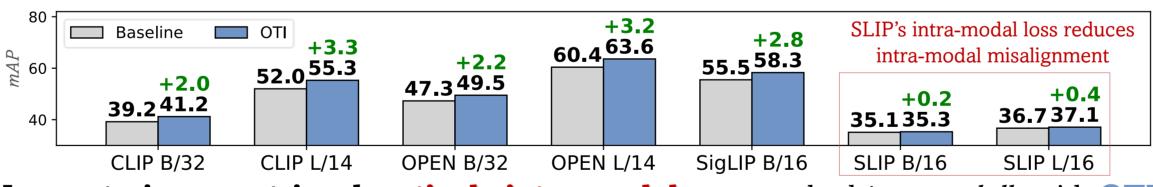
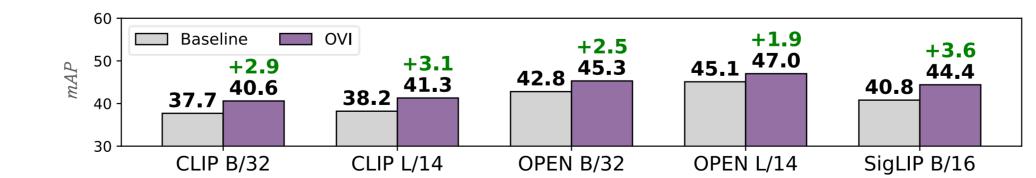
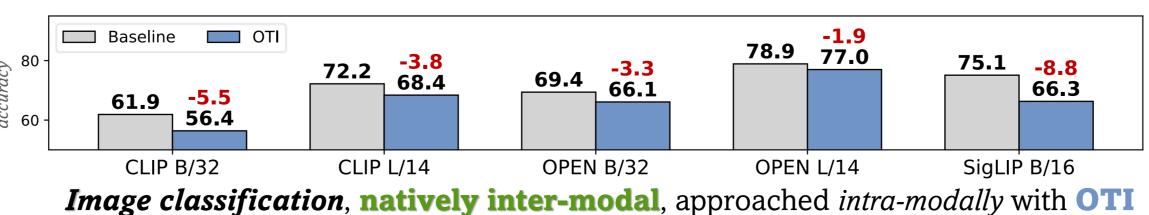


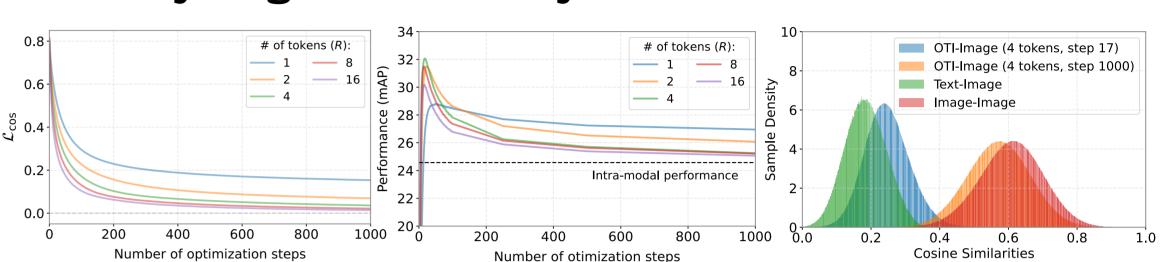
Image-to-image retrieval, natively intra-modal, approached inter-modally with OTI



Text-to-text retrieval, natively intra-modal, approached inter-modally with OVI



 $oxedsymbol{-}5.$  Analyzing the Modality Inversion $oxedsymbol{-}$ 



Performance peaks early during optimization, before *features drift* toward the native manifold. While a lower number of learnable tokens (R = 1) offers more robustness, larger values accelerate convergence and improve peak performance.

# $oldsymbol{-}$ 6. Role of the modality gap-

- We fine-tune CLIP on COCO using different temperatures, preserving and closing the modality gap
- ☐ Modality inversion benefit correlates with the magnitude of the modality gap

Algorithm 1 OTI

Fine-tuning Temperature	Inter modal	CUB	SOP	$\mathcal{R} ext{Oxfo}$	$\mathcal{R}$ Paris	Cars	Averag
$ au=1 \ (no\ gap)$	X ✓	<b>15.9</b> 14.0	<b>23.7</b> 20.4	<b>29.3</b> 26.7	<b>46.6</b> 43.1	<b>19.3</b> 17.4	<b>27.0</b> 24.2
$\tau = 0.01$ (CLIP gap)	X ✓	24.0 <b>24.1</b>	35.0 <b>35.2</b>	43.1 <b>44.0</b>	68.6 <b>70.2</b>	25.7 <b>27.6</b>	39.3 <b>40.2</b>

# **─7. OTI** and **OVI** pseudo-algorithms & Source Code!—

Algorithm 2 OVI

1: <b>Input:</b> Image $I$ , number of pseudo-tokens $R$ ,
number of optimization steps $S$
2: Initialize $v^* = \{v_1^*, v_2^*, \dots, v_R^*\}$
3: Extract image features: $\psi_I = f_{\theta}(I)$
4: for $s = 1$ to $S$ do
5: Form $\overline{Y}_{v^*} = [E_v(\text{``a photo of''}), v^*]$
6: Extract text features: $\psi_T = g_{\phi}(\overline{Y}_{v^*})$
7: Compute loss: $\mathcal{L}_{\cos} = 1 - \cos(\psi_I, \psi_T)$
8: Update $v^*$ to minimize $\mathcal{L}_{\cos}$
9: end for
10: <b>Output:</b> OTI-inverted features $\psi_T = g_{\phi}(\overline{Y}_{v^*})$

1: <b>Input:</b> Text $Y$ , number of pseudo-patches $P$ ,
number of optimization steps $S$
2: Initialize $w^* = \{w_1^*, w_2^*, \dots, w_P^*\}$
3: Extract text features: $\psi_T = g_{\phi}(E_v(Y))$
4: for $s=1$ to $S$ do
5: Form input $\bar{I}_{w^*}$ using ??
6: Extract image features: $\psi_I = f_{\theta}(\bar{I}_{w^*})$
7: Compute loss: $\mathcal{L}_{\cos} = 1 - \cos(\psi_I, \psi_T)$
8: Update $w^*$ to minimize $\mathcal{L}_{\cos}$
9: end for
10: <b>Output:</b> OVI-inverted features $\psi_I = f_{\theta}(\bar{I}_{w^*})$

The code implementing **OTI** and **OVI** with all the different backbones and on all the evaluated datasets is finally available. Feel free to explore, use and contribute!

